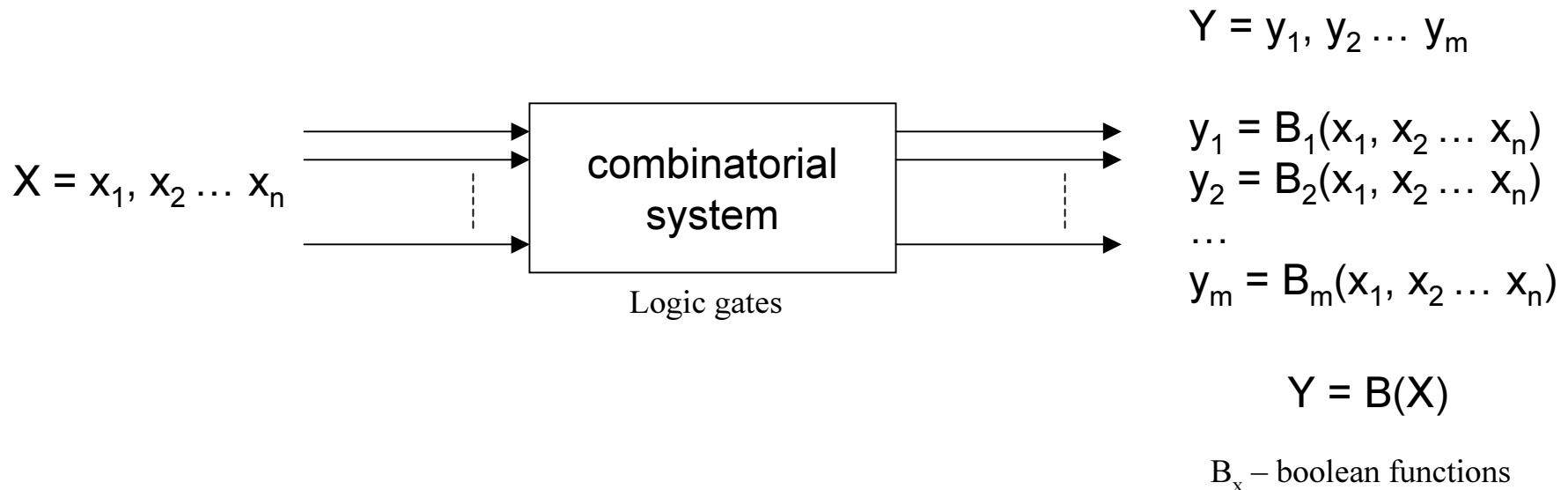


Combinatorial systems



Any change of input signal X modifies the output signal Y with maximum speed limited by the signal propagation time.

Output vector Y is a function of current value of X in any moment.

Combinatorial systems - description

np.

$$y(a, b, c) = a^*(b+\bar{c}) + (\bar{a}+b)^*c$$

Truth table

a	b	c	y(a, b, c)
0	0	0	0
0	0	1	1
0	1	0	0
0	1	1	1
1	0	0	1
1	0	1	0
1	1	0	1
1	1	1	1

Sum of maxterms

$$y(a, b, c) = \bar{a}\bar{b}c + \bar{a}bc + a\bar{b}\bar{c} + a\bar{b}c + abc$$

Product of minterms

$$y(a, b, c) = (a+b+c) (a+\bar{b}+c) (\bar{a}+b+\bar{c})$$

Optimization algorithms of boolean functions !

Boolean algebra

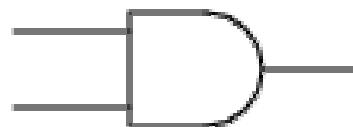
Identity element	$a+0=a$	$a^*1=a$
Commutativity	$a+b=b+a$	$a^*b=b^*a$
Associativity	$a+(b+c)=(a+b)+c$	$a^*(b^*c)=(a^*b)^*c$
Distributivity	$a+(b^*c)=(a+b)^*(a+c)$	$a^*(b+c)=(a^*b)+(a^*c)$
Complement	$a+\bar{a}=1$	$a^*\bar{a}=0$
Idempotency	$a+a=a$	$a^*a=a$
Complement	$a+1=1$	$a^*0=0$
Absorption	$a+a^*b=a$	$a^*(a+b)=a$
Element Elimination	$a+\bar{a}^*b=a+b$	$a^*(\bar{a}+b)=a^*b$
De Morgan's Laws	$\overline{a+b}=\bar{a}^*\bar{b}$	$\overline{a^*b}=\bar{a}+\bar{b}$

Logic gates



NOT

$$F = \overline{a}$$



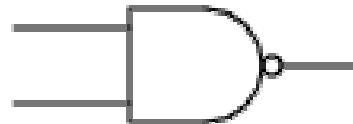
AND

$$F = a \cdot b$$



OR

$$F = a + b$$



NAND

$$F = \overline{a \cdot b}$$



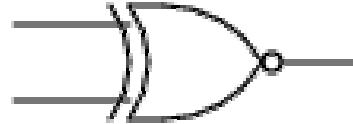
NOR

$$F = \overline{a + b}$$



XOR

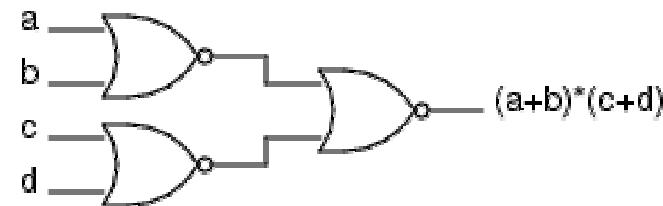
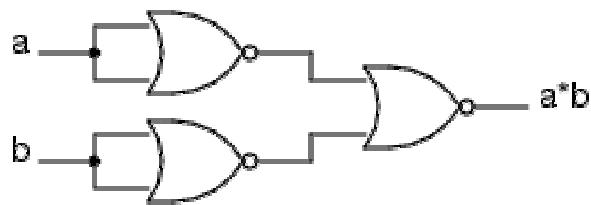
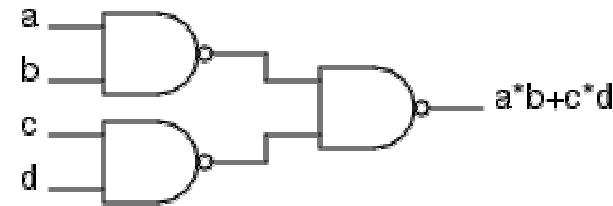
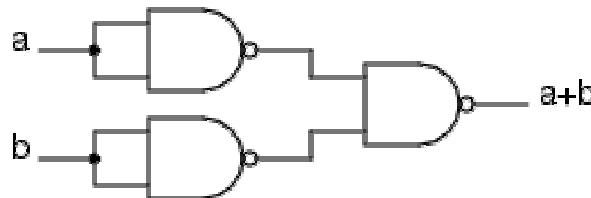
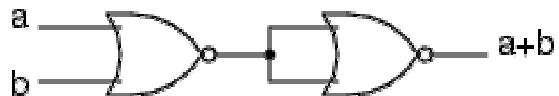
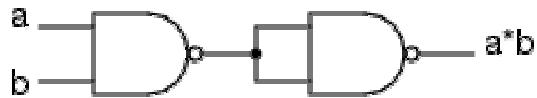
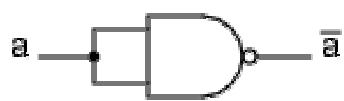
$$F = a \oplus b$$



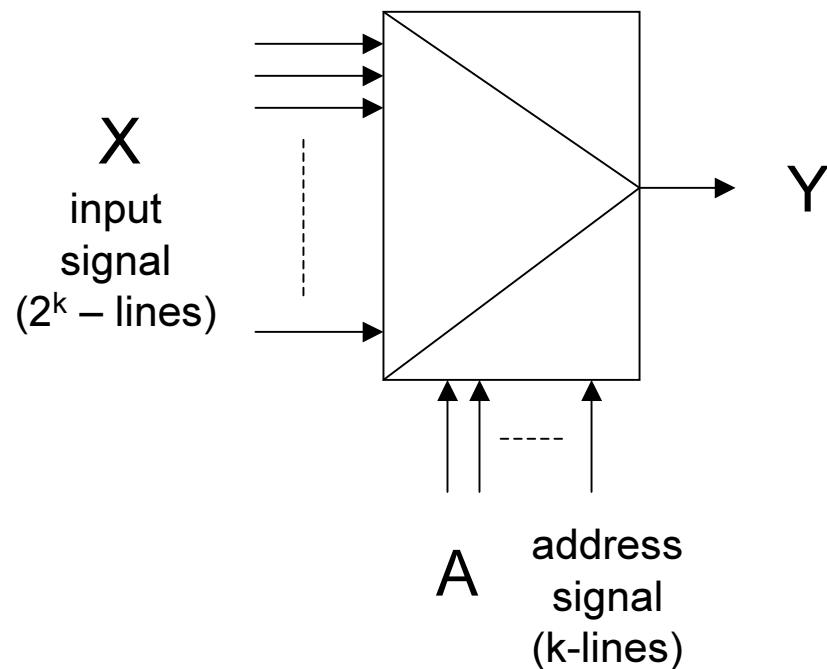
XNOR

$$F = \overline{a \oplus b}$$

Realisation of boolean functions

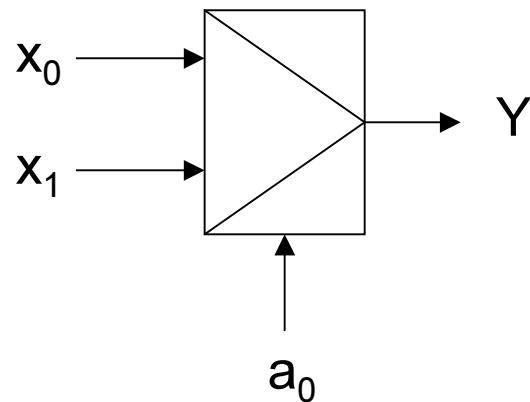


Multiplexers

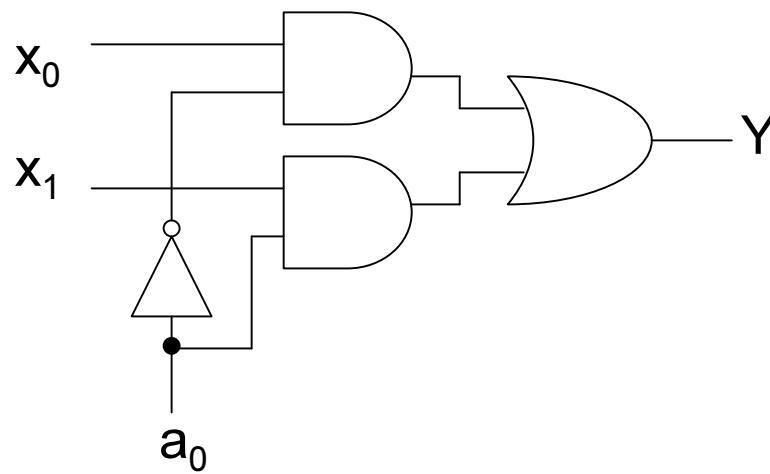


$$Y = x_0 \cdot \overline{a_{k-1}} \cdot \dots \cdot \overline{a_1} \cdot \overline{a_0} + x_1 \cdot \overline{a_{k-1}} \cdot \dots \cdot \overline{a_1} \cdot a_0 + \dots + x_{2^k-1} \cdot a_{k-1} \cdot \dots \cdot a_1 \cdot a_0$$

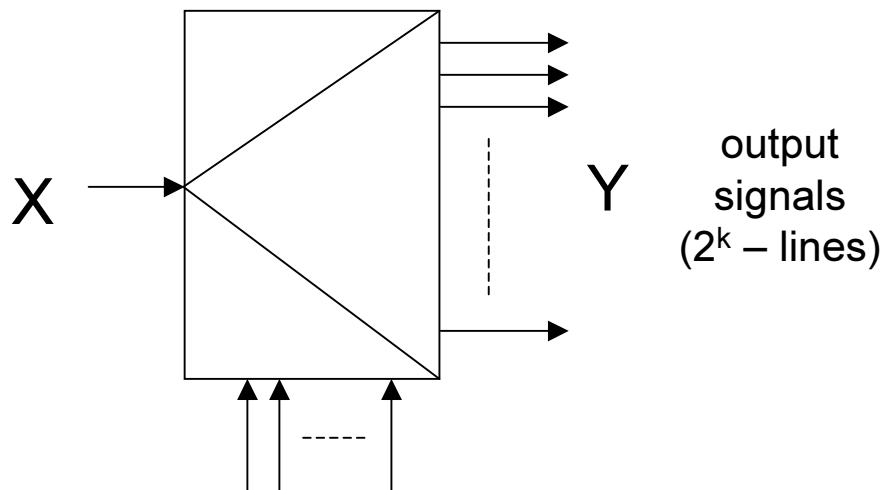
Multiplexer 2x1



$$Y = x_0 \cdot \overline{a}_0 + x_1 \cdot a_0$$



Demultiplexers



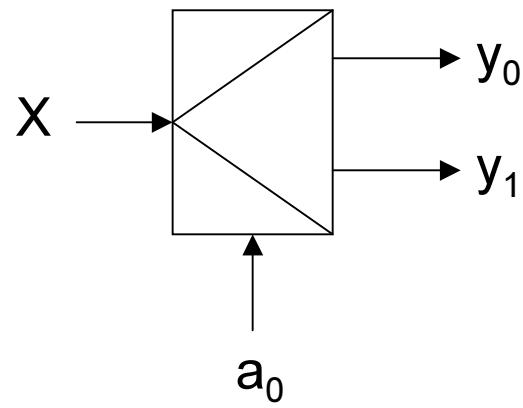
A
address
signal
(k-lines)

$$y_0 = X \cdot \overline{a_{k-1}} \cdot \dots \cdot \overline{a_1} \cdot \overline{a_0}$$
$$y_1 = X \cdot \overline{a_{k-1}} \cdot \dots \cdot \overline{a_1} \cdot a_0$$

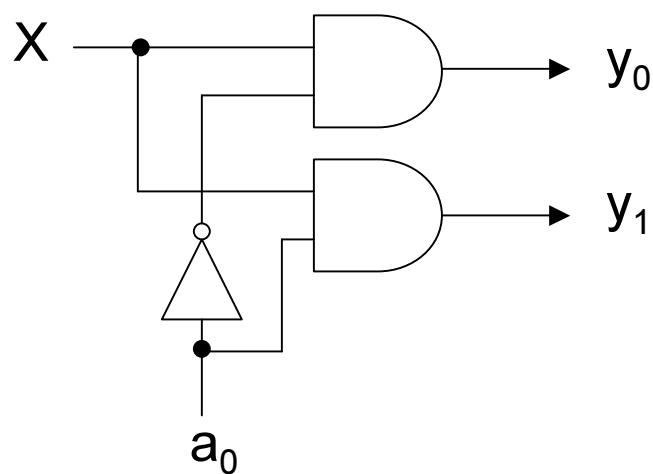
...

$$y_{2^{k-1}} = X \cdot a_{k-1} \cdot \dots \cdot a_1 \cdot a_0$$

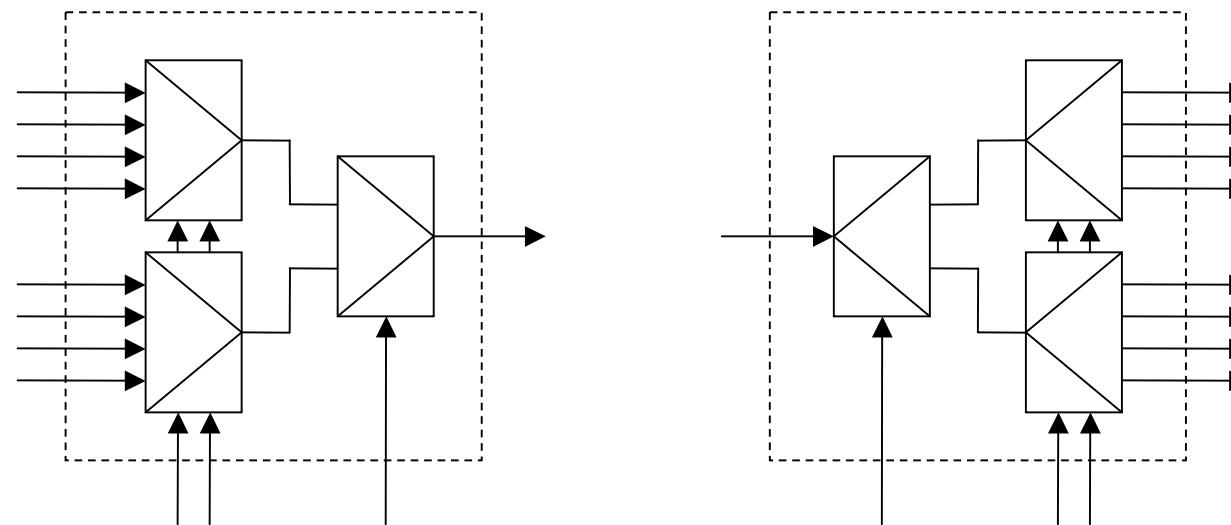
Demultiplexer 1x2



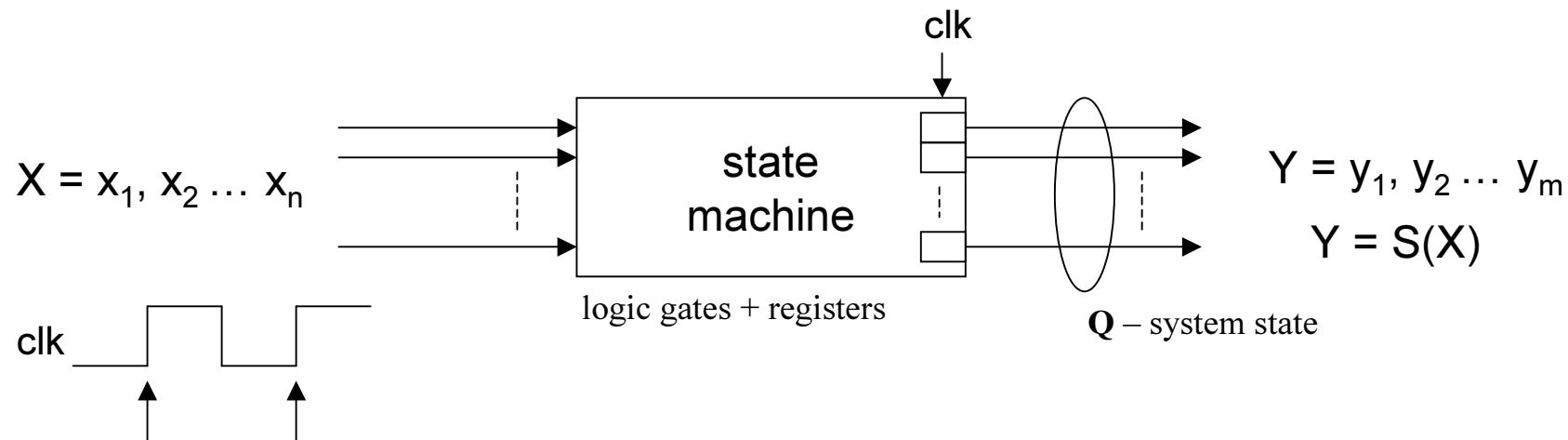
$$y_0 = X \cdot \overline{a_0}$$
$$y_1 = X \cdot a_0$$



Cascades of (de)multiplexers



State machines

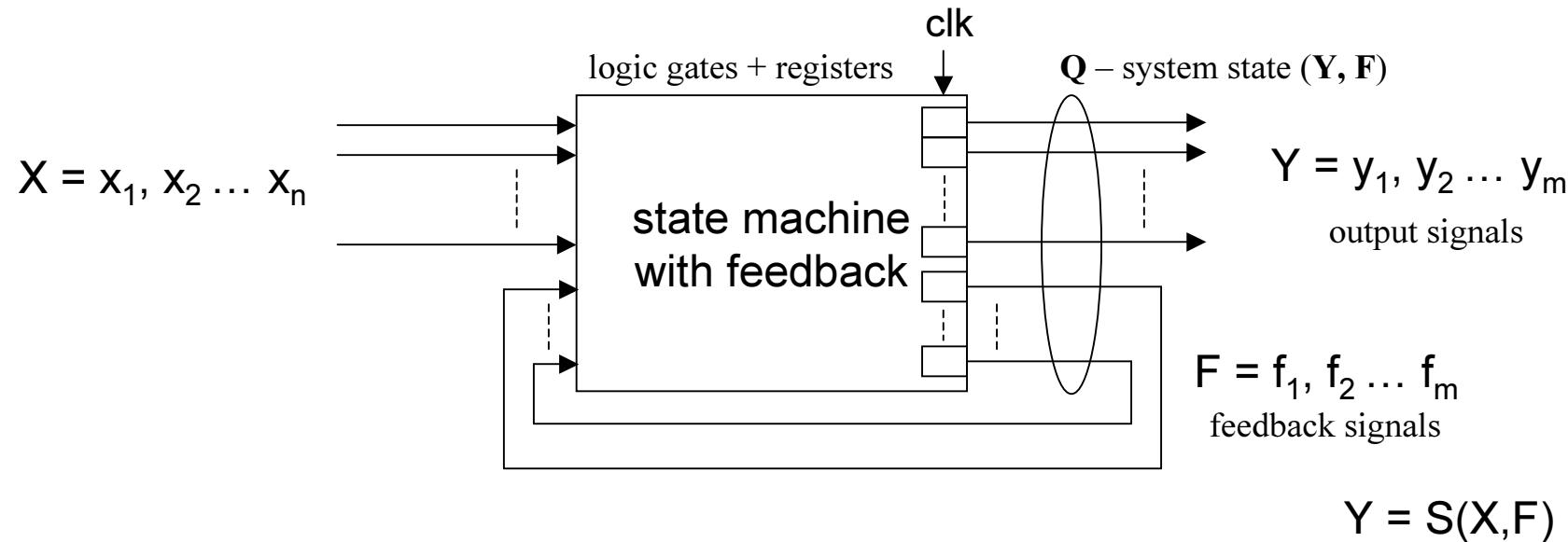


Any change of output signal Y is only possible at the change of the clock signal to memory elements (edge triggered write operation)

Output signals Y (when changed) are the function of input signal X only in the moment of the clock edge. In any other moment, the output Y is stable and independent of any change in input X .

Description of state machine consists in enumerating the output states Q and the sequence of their change (state diagram).

State machine with feedback

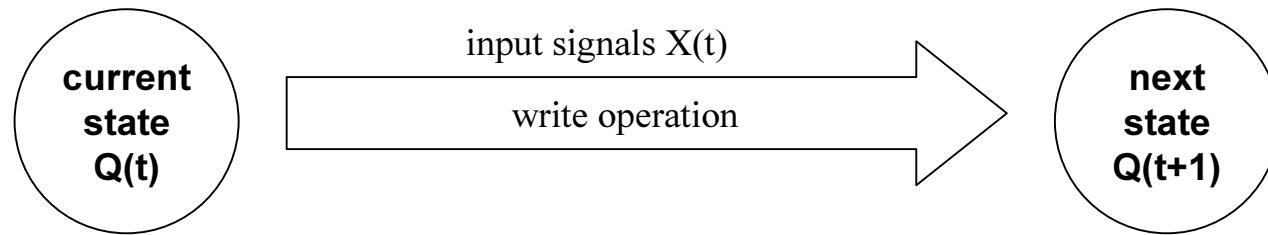


Change of Y (and Q) is synchronised with clock signal.

Next state of the system depends on current input signals X and on current system state F (feedback).

System state can be described by set of values Y, F and sequence of their change (state diagram).

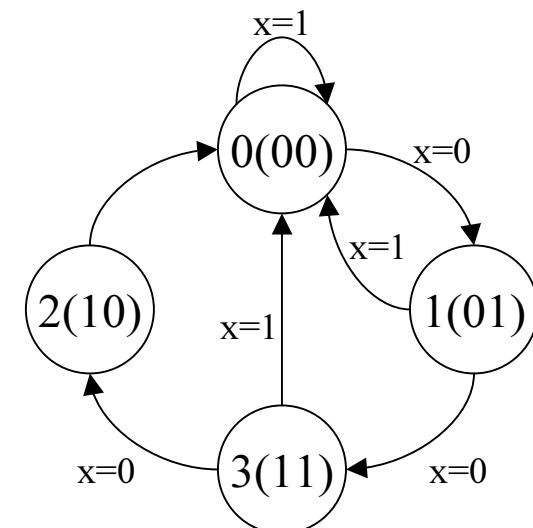
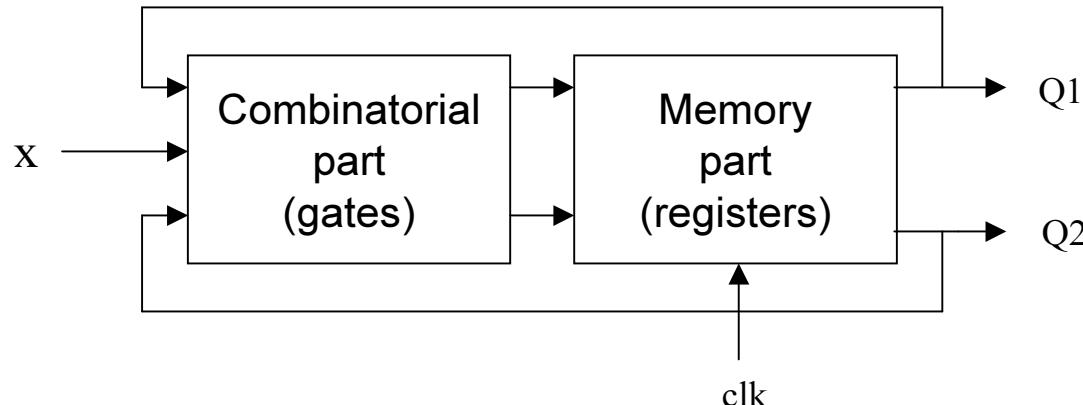
State diagrams



Next state depends on:

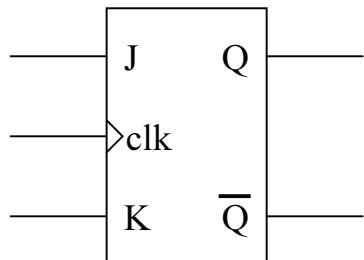
- 1) current state (signals Y, F)
- 2) input signals at the moment of write

Example



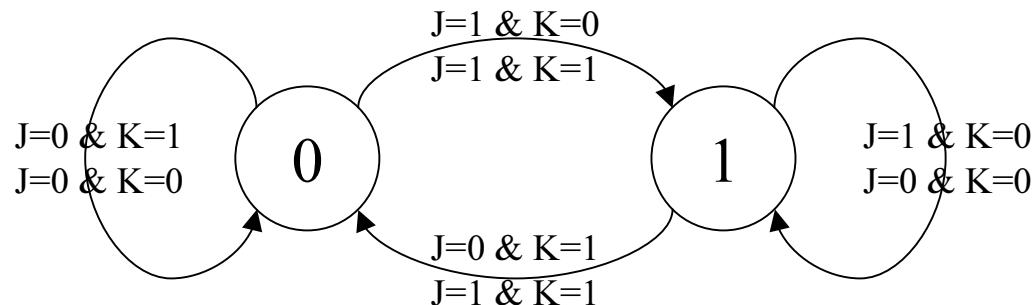
State diagrams - examples

JK Flip-flop

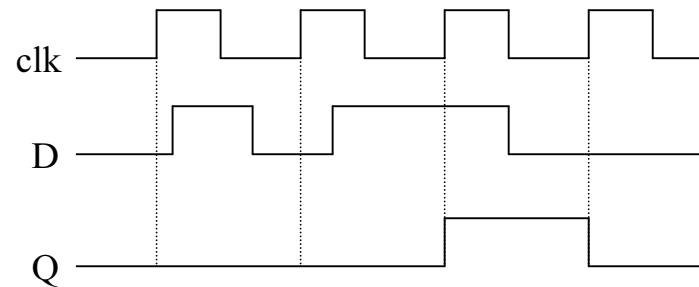
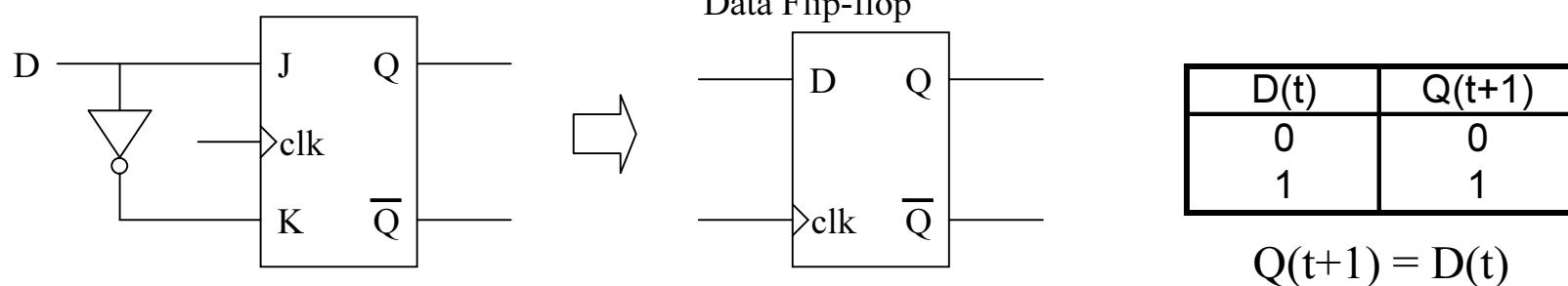


J(t)	K(t)	Q(t+1)
0	0	Q(t)
0	1	0
1	0	1
1	1	$\bar{Q}(t)$

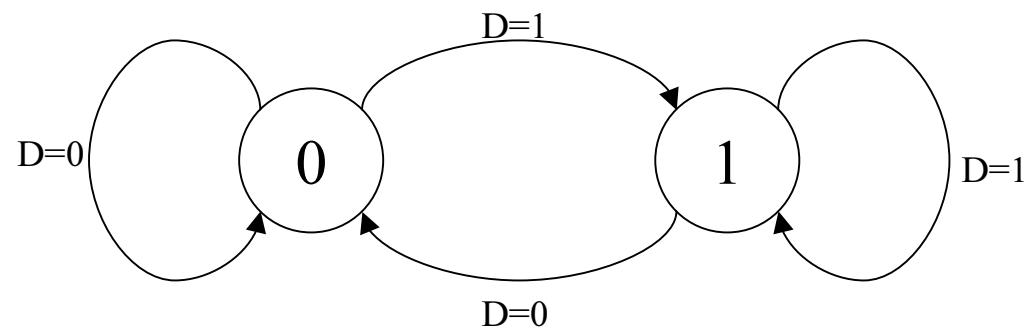
$$Q(t+1) = J(t) \bar{Q}(t) + \bar{K}(t) Q(t)$$



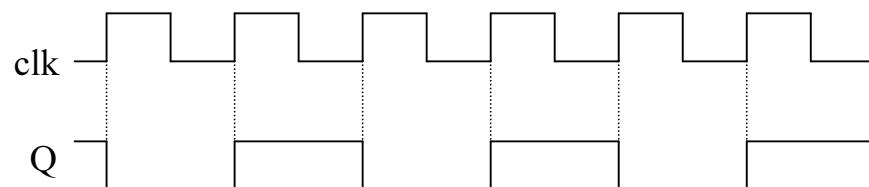
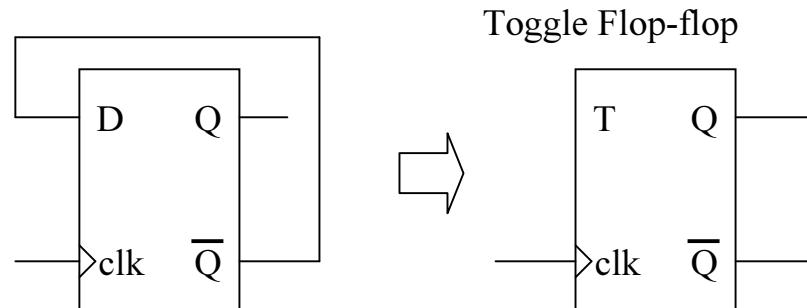
State diagrams - examples



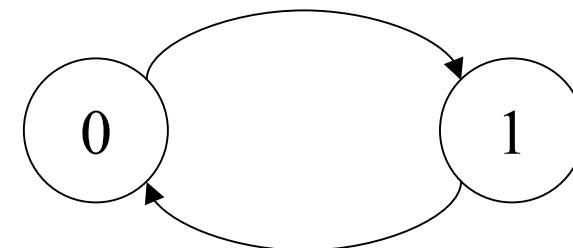
$$Q(t+1) = D(t)$$



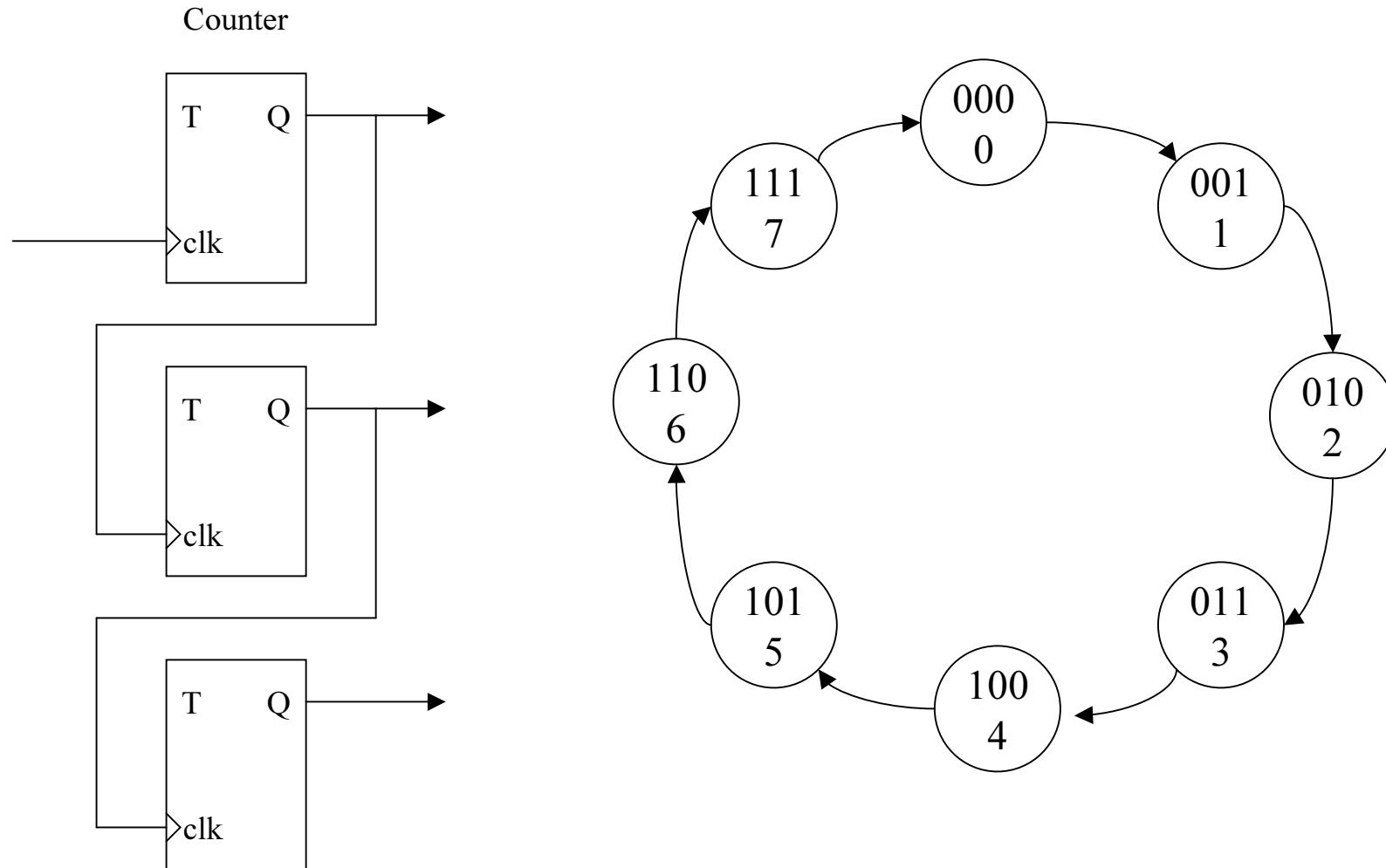
State diagrams - examples



$$Q(t+1) = \bar{Q}(t)$$



State diagrams - examples



State diagram - examples

