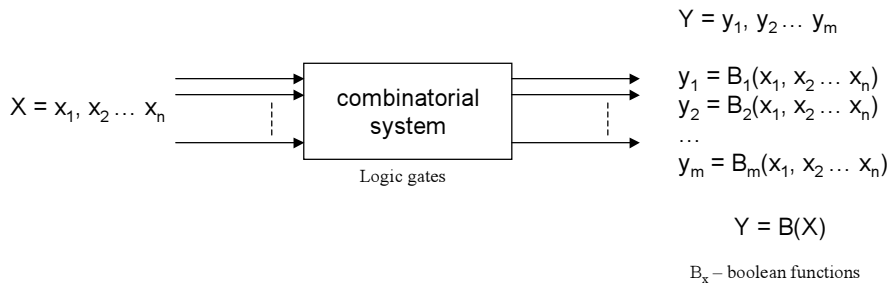


## Combinatorial systems



Any change of input signal X modifies the output signal Y with maximum speed limited by the signal propagation time.

Output vector Y is a function of current value of X in any moment.

## Combinatorial systems - description

np.  
 $y(a, b, c) = a*(b+\bar{c}) + (\bar{a}+b)*c$

Truth table

a	b	c	y(a, b, c)
0	0	0	0
0	0	1	1
0	1	0	0
0	1	1	1
1	0	0	1
1	0	1	0
1	1	0	1
1	1	1	1

Sum of maxterms  
 $y(a, b, c) = \bar{a}\bar{b}c + \bar{a}bc + a\bar{b}\bar{c} + abc + abc$

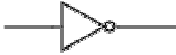
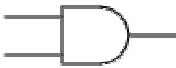





Product of minterms  
 $y(a, b, c) = (a+b+c) (a+\bar{b}+c) (\bar{a}+b+\bar{c})$

Optimization algorithms of boolean functions !

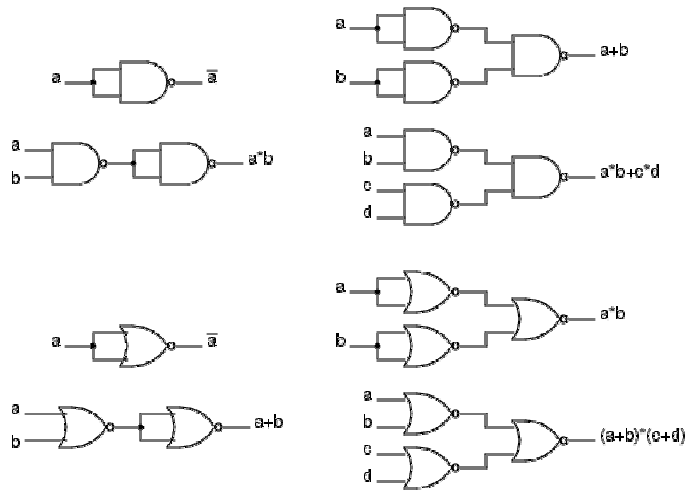
## Boolean algebra

Identity element	$a+0=a$	$a*1=a$
Commutativity	$a+b=b+a$	$a*b=b*a$
Associativity	$a+(b+c)=(a+b)+c$	$a*(b*c)=(a*b)*c$
Distributivity	$a+(b*c)=(a+b)*(a+c)$	$a*(b+c)=(a*b)+(a*c)$
Complement	$a+\bar{a}=1$	$a*\bar{a}=0$
Idempotency	$a+a=a$	$a*a=a$
Complement	$a+1=1$	$a*0=0$
Absorption	$a+a*b=a$	$a*(a+b)=a$
Element Elimination	$a+\bar{a}*b=a+b$	$a*(\bar{a}+b)=a*b$
De Morgan's Laws	$\overline{a+b}=\bar{a}*\bar{b}$	$\overline{a*b}=\bar{a}+\bar{b}$

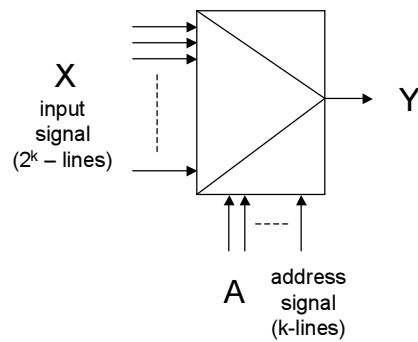
## Logic gates

	NOT	$F = \bar{a}$
	AND	$F = a \cdot b$
	OR	$F = a + b$
	NAND	$F = \overline{a \cdot b}$
	NOR	$F = \overline{a + b}$
	XOR	$F = a \oplus b$
	XNOR	$F = \overline{a \oplus b}$

## Realisation of boolean functions

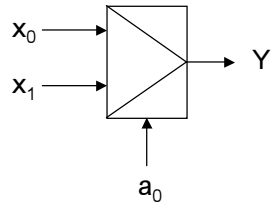


## Multiplexers

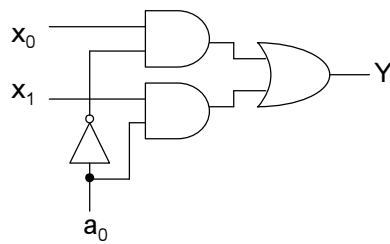


$$Y = x_0 \cdot \overline{a_{k-1}} \cdot \dots \cdot \overline{a_1} \cdot \overline{a_0} + x_1 \cdot \overline{a_{k-1}} \cdot \dots \cdot \overline{a_1} \cdot a_0 + \dots + x_{2^k-1} \cdot a_{k-1} \cdot \dots \cdot a_1 \cdot a_0$$

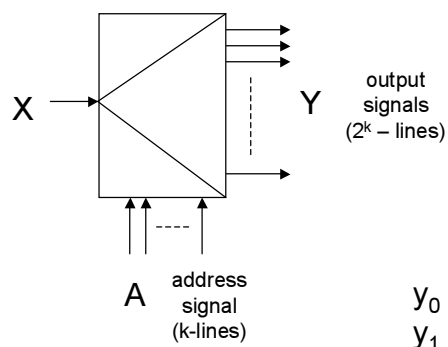
## Multiplexer 2x1



$$Y = x_0 \cdot \overline{a_0} + x_1 \cdot a_0$$



## Demultiplexers



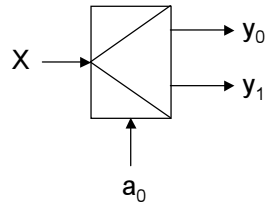
$$y_0 = X \cdot \overline{a_{k-1}} \cdot \dots \cdot \overline{a_1} \cdot \overline{a_0}$$

$$y_1 = X \cdot \overline{a_{k-1}} \cdot \dots \cdot a_1 \cdot \overline{a_0}$$

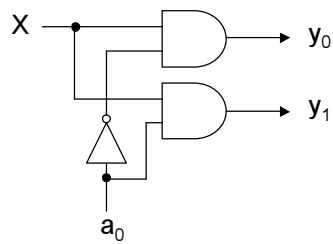
$$\dots$$

$$y_{2^k-1} = X \cdot a_{k-1} \cdot \dots \cdot a_1 \cdot a_0$$

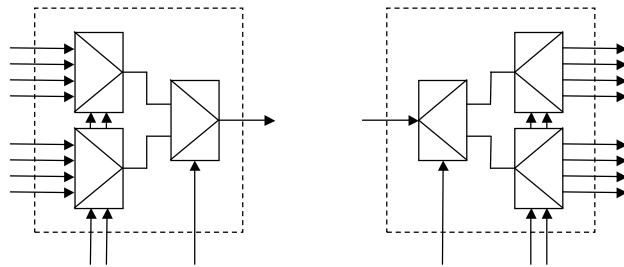
## Demultiplexer 1x2



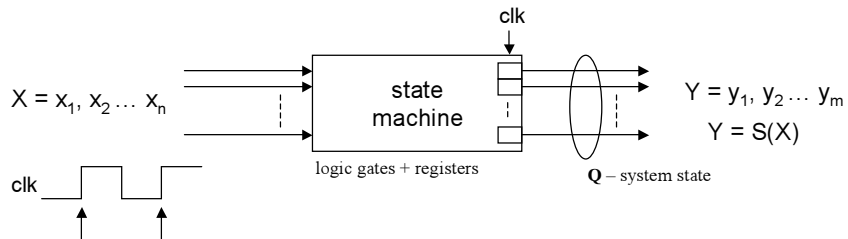
$$y_0 = X \cdot \overline{a_0}$$
$$y_1 = X \cdot a_0$$



## Cascades of (de)multiplexers



## State machines

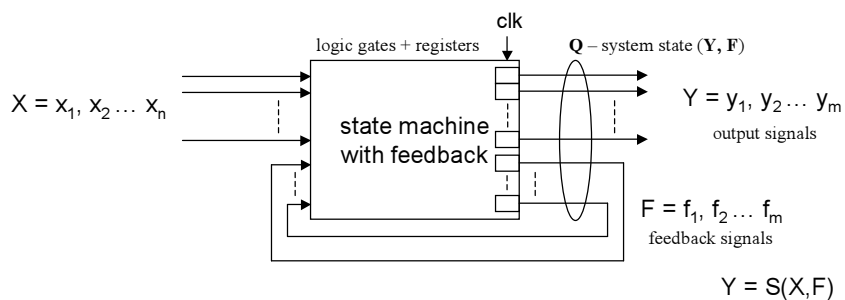


Any change of output signal  $Y$  is only possible at the change of the clock signal to memory elements (edge triggered write operation)

Output signals  $Y$  (when changed) are the function of input signal  $X$  only in the moment of the clock edge. In any other moment, the output  $Y$  is stable and independent of any change in input  $X$ .

Description of state machine consists in enumerating the output states  $Q$  and the sequence of their change (state diagram).

## State machine with feedback

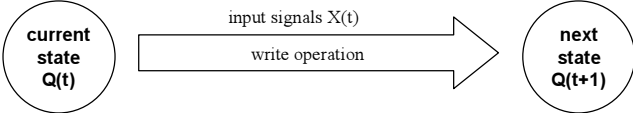


Change of  $Y$  (and  $Q$ ) is synchronised with clock signal.

Next state of the system depends on current input signals  $X$  and on current system state  $F$  (feedback).

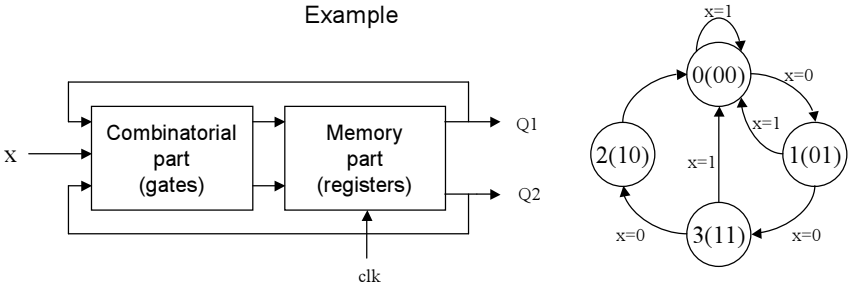
System state can be described by set of values  $Y, F$  and sequence of their change (state diagram).

# State diagrams

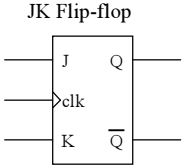


- Next state depends on:
- 1) current state (signals  $Y, F$ )
  - 2) input signals at the moment of write

Example

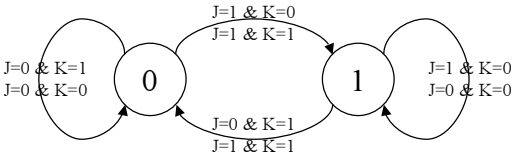


# State diagrams - examples

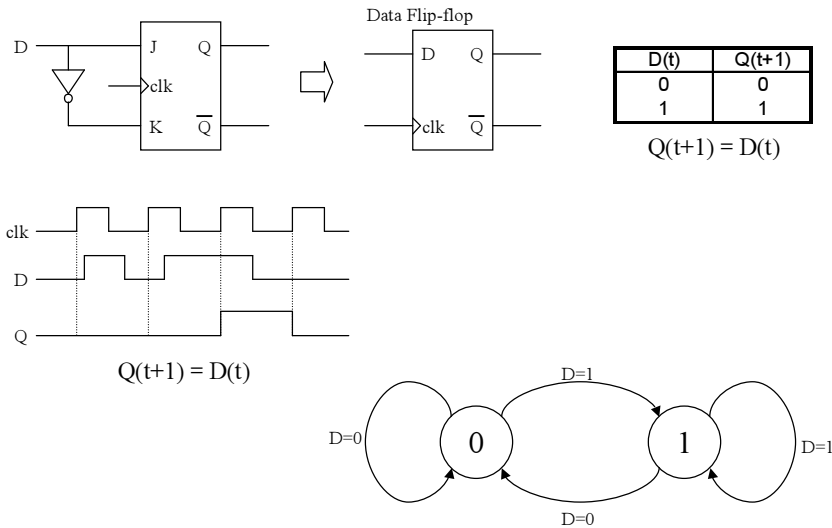


$J(t)$	$K(t)$	$Q(t+1)$
0	0	$Q(t)$
0	1	0
1	0	$\bar{1}$
1	1	$\bar{Q}(t)$

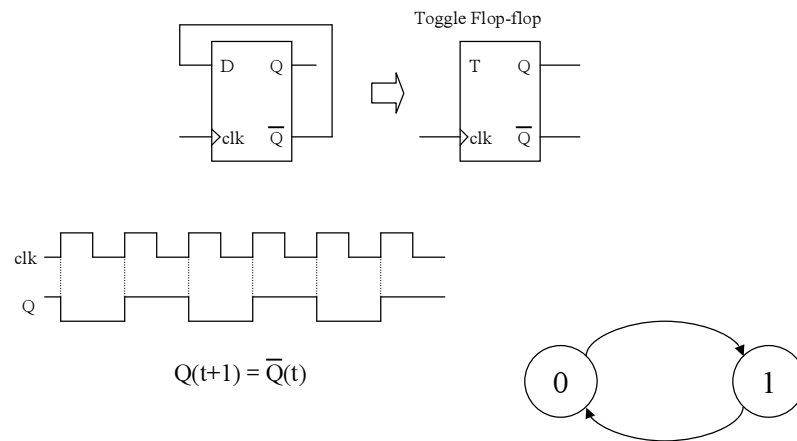
$$Q(t+1) = J(t) \bar{Q}(t) + \bar{K}(t) Q(t)$$



## State diagrams - examples

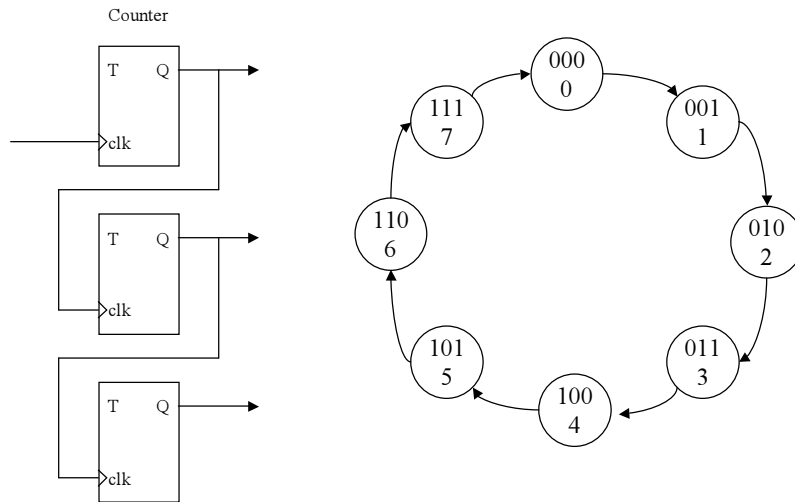


## State diagrams - examples





## State diagrams - examples



## State diagram - examples

